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Please amend the following paragraphs in the Specification according to the amendments below.

Only a tubular belt constructed by this invention may be routed to make, for example, a continuous 360° turn having a radius as little as only ten times its diameter, and be operational in such a configuration. This construction permits turns having radii as small as 200, 100, 50, 30, 20 or even 10 times the diameter of the belt, which is significantly smaller than turns having a radii that are 300 times the diameter for belts according to the prior art. For example, using the designs incorporated herein, it has been demonstrated that a belt 6" in diameter are operable in a curve having a radius of $\underline{5}$ 6'.

The rib cast 61 is located on the other side of the bottom of the web 52. Rib casts 61 through 64 are typical for each of the vertical webs 52 through 55. A typical rib cast has a wedge-like cross section, with an indent 65 on the bottom side of the rib, which corresponds to the section of the bottom 40 of the anchor strips 35 through 38. Another typical detail of the rib casts are apexs 66 through 69. The bottom surfaces of the cast ribs 61 through 64 (including bottom surface of the indents) are made as an arc of the same radius R_L as plate 60. Also, the heights of the webs 52 through 55 vary in such a way that all of the rib casts generate one arc of radius R_L. The rib 56 is connected to the arc plate 57, whose radius is <u>correlated</u> equal to the design radius of the future tubular belt in the vicinity of the longitudinal edge (R₂ in FIG. 1). A stiffener 59 joins the rib 56 and the plate 57 and is located in the same space as the stiffener 58.

Appl. No. 10/782,655 Filed February 19, 2004

The guided grip device 70 is used to stretch the inner layer(s) 11 of the tubular belt to the design proportions, and to hold it in that stretched (prestressed) position during the technological time of bonding inner and outer layers together into one monolithic entity. The guided grip device 70 incorporates a guide portion and a grip portion. The guide portion of guided grip device 70 comprises a special profile guide 71 with welded strips 72 – inside of the profile 71 – and strip 73 72 outside of the profile 71.

[00101] The gaps 112 are filled with raw rubber or with other material 113, which, after processing, will join monolithically all turns of the rubber spring 104b into one tubular shape, as shown on the right portion of FIG. 29. Following equation (1), it can be derived that the elastic rubber spring 104b, which was made with radius R5 and then wound up with radius R6, possessed, after manufacturing on mandrel 110, the inner bending moment

$$Mi = EI (R6 - R5) / R5R6$$
 (5)

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